

AMKAH ABBAS

Q1. a) i) $G(s) = \frac{(s+3)}{(s^2+4s+5)(s+4)}$

$(s-2-j1)(s-2+j1)$

$(s^2 - 2s + j^2 - 2s + 4 - j^2 - js + 2j + 1)$
 $s^2 + 4s + 5$

ii) asymptote point $= \frac{-4-2-2-(-8)}{3-1}$
 $= \frac{-4-2-2+8}{2}$
 $= \frac{0}{2} = 0$

$\theta_a = \left(\frac{2k+1}{3} \right) \pi$

$= 60^\circ, 180^\circ, 300^\circ$

$= \frac{\pi}{3}, \pi, \frac{5\pi}{3}$

iii) Angle of departure;

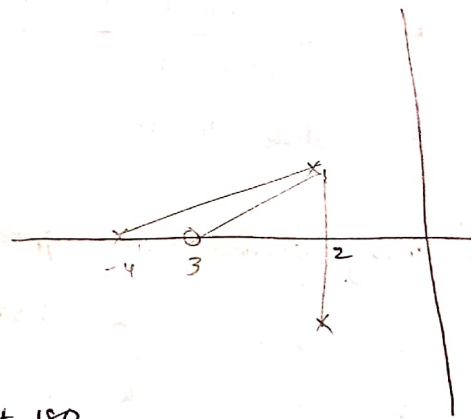
$\theta_d = 90 + \tan^{-1} \frac{1}{2} = 180$

$\theta = \sum \text{angle zeros} - \sum \text{angle pole} + 180$

$= \tan^{-1} \left(\frac{1}{1} \right) - 90 - \tan^{-1} \frac{1}{2} + 180$

$= 45 - 90 - 26.56 + 180$

$= 108.44$



b) 10% overshoot $\xi = 0.59$ $\omega_n = 4.08 \text{ rad/s}$

i) Dominant closed looped.

$$\begin{aligned} \text{Real} &= -\xi \omega_n \\ &= -0.59(4.08) \\ &= -2.41 \end{aligned}$$

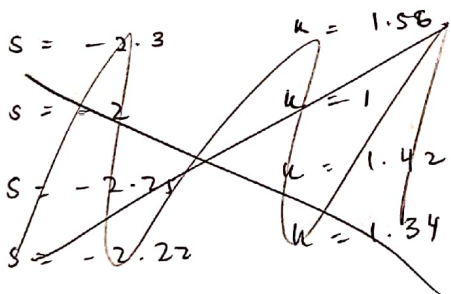
$$\begin{aligned} \text{Img} &= j \omega_n \sqrt{1 - \xi^2} \\ &= j 4.08 \sqrt{1 - 0.59^2} \\ &= j 3.29 \end{aligned}$$

Dominant closed loop = $-2.41 \pm j3.29$

ii) $K = \frac{(s^2 + 4s + 5)(s + 4)}{(s + 3)}$

$K = 10.96$

iii) verify second order approximation.



$s = -6$ $k = 11.33$

$\text{ratio} = \frac{6}{2.41} = 2.49 < 5$

\therefore 2nd order app not valid.

$\text{ratio} = \frac{|-2.22|}{|-2.41|} = 0.92 < 5$

iv) $T_s = \frac{4}{2.41} = 1.66 \text{ s}$ $T_p = \frac{\pi}{3.29} = 0.95 \text{ s}$

$$\begin{aligned} K_p &= \lim_{s \rightarrow 0} \frac{10.96 (s + 3)}{(s^2 + 4s + 5)(s + 4)} \\ &= 1.64 \end{aligned}$$

$$\begin{aligned} e_{ss} &= \frac{1}{1 + K_p} = \frac{1}{1 + 1.64} \\ &= 0.38 \end{aligned}$$

$$Q2. \quad G(s) = \frac{k(s^2 - 2s + 8)}{(s+3)(s^2 + 4s + 5)}$$

$$s_d = -0.88 \pm j1.72, \quad 20\% \text{ OS}$$

$$\xi = \frac{-\ln 0.2}{\sqrt{\pi^2 + \ln(0.2)^2}} = 0.46$$

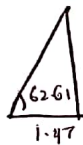
$$\theta = \cos^{-1} 0.46 = 62.61$$

a) $T_s = \frac{3}{5}$ of uncompensated value.

$$T_{s \text{ old}} = \frac{4}{0.88} = 4.54s$$

$$T_{s \text{ new}} = \frac{4}{|\text{Re } s|} = \frac{3}{5}(4.54) = 1.47s$$

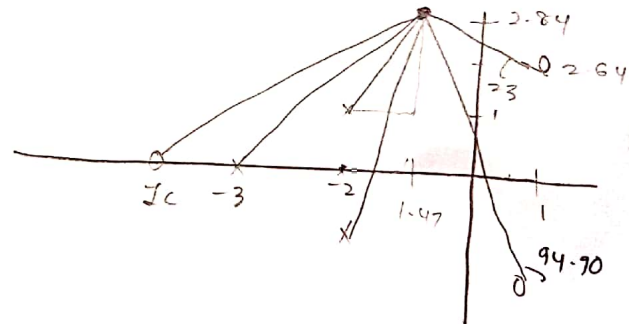
$$T_p \text{ new} = \frac{\tan 62.61}{1.47} = 2.84$$



$$s = -1.47 \pm j2.84$$

$$G_{pd} = s + z$$

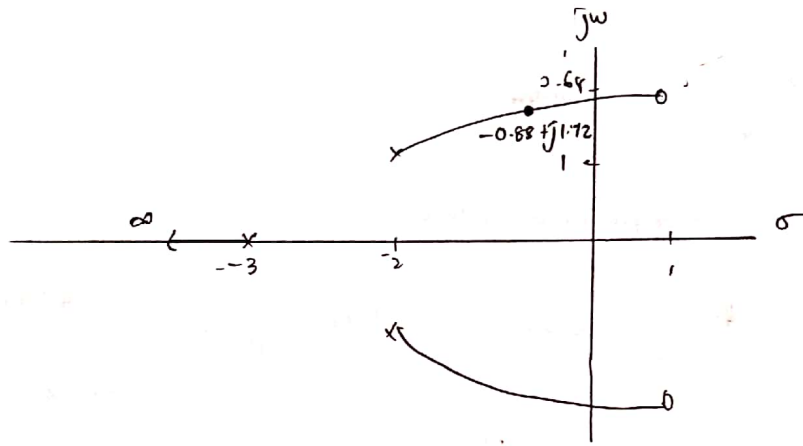
$$TF = \frac{k(s+z)(s^2 - 2s + 8)}{(s+3)(s^2 + 4s + 5)}$$



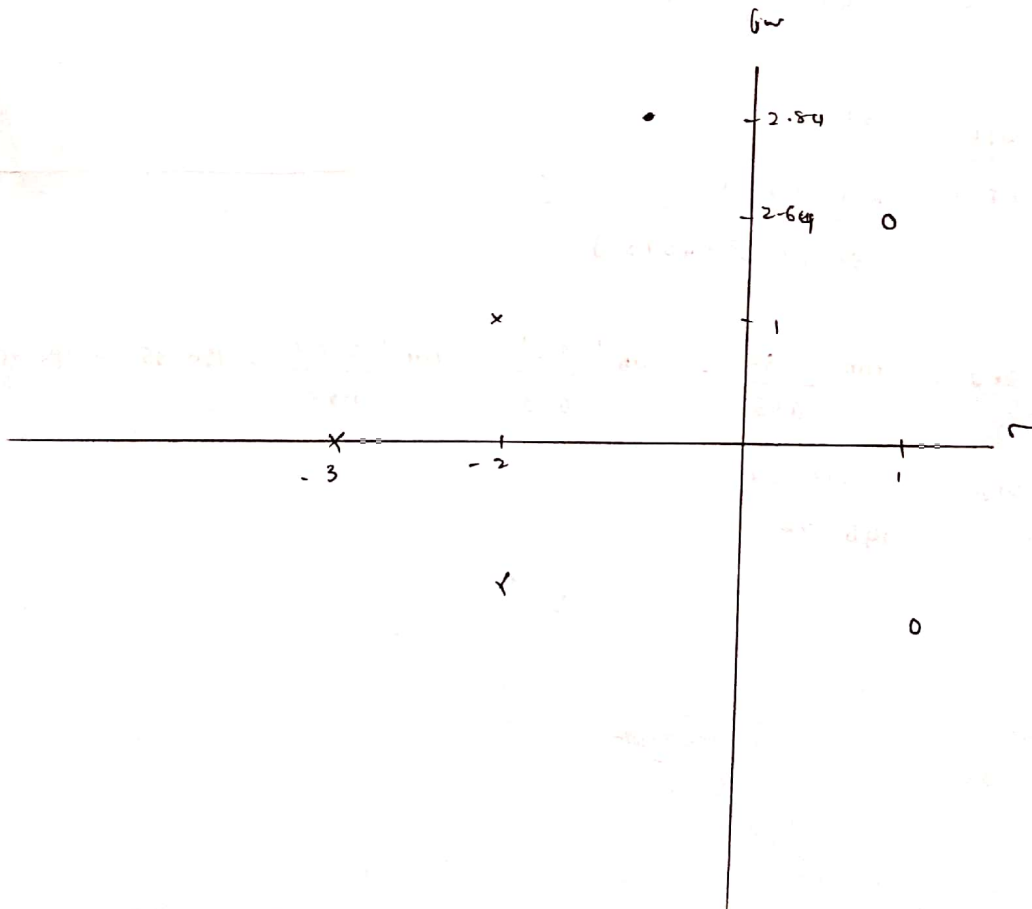
$$\angle s+z = \tan^{-1} \frac{1.84}{0.53} = \tan^{-1} \frac{4.31}{0.53} = \tan^{-1} \frac{2.84}{1.53} + 156.95 + 94.90 = -180$$

$$\angle s+2 = -213.24 = 146.76$$

b) sketch
Uncompensated.



Compensated



Q3 . $G(s) = \frac{12}{s(s+6)} = \frac{12}{6s(\frac{s}{6}+1)}$

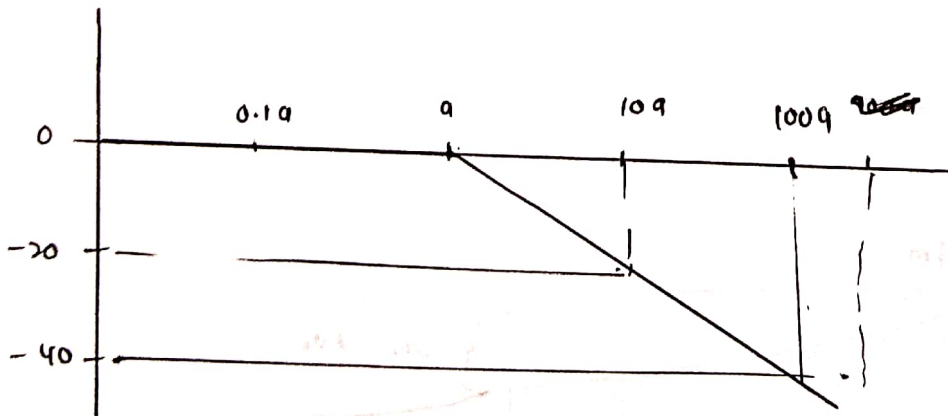
a)

i) magnitude

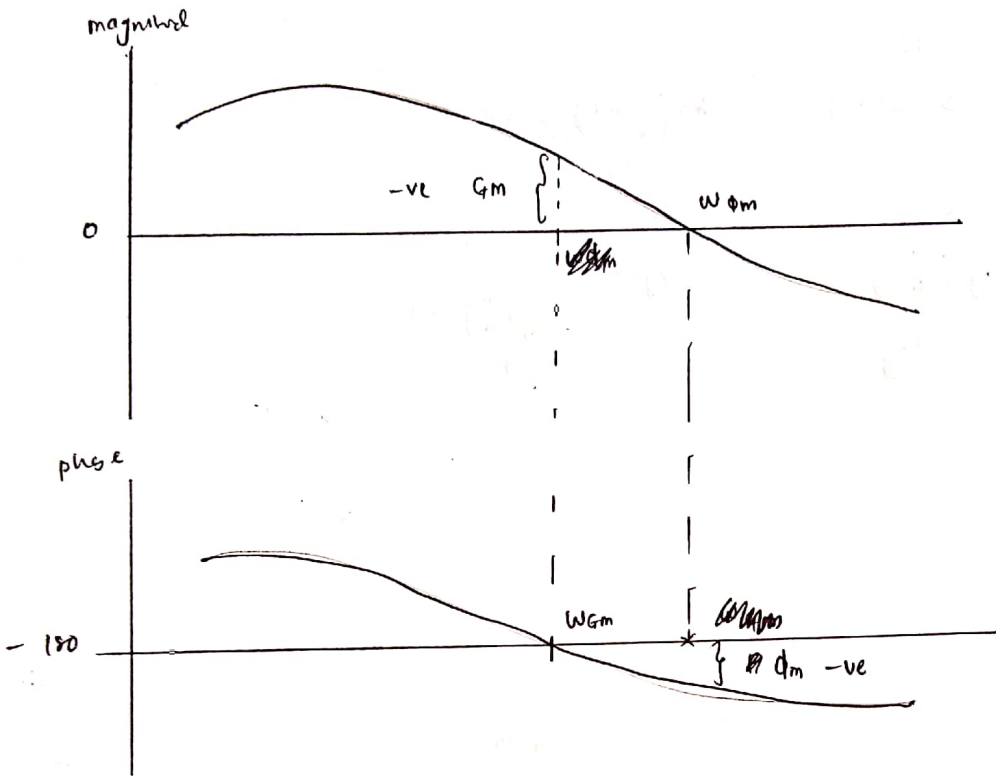
$$|G(j\omega)| = \log\left(\frac{1}{\omega}\right) = -20 \log \omega$$

$$|G(j\omega)| = \frac{1}{\sqrt{\left(\frac{\omega}{a}\right)^2 + 1}}$$

b) sketch $G(s) = \frac{100}{(s+10)}$ $a=10$



Un Stable



stable

